

# **Classical molecular dynamics simulations of condensed matter**

***Kostya Trachenko***

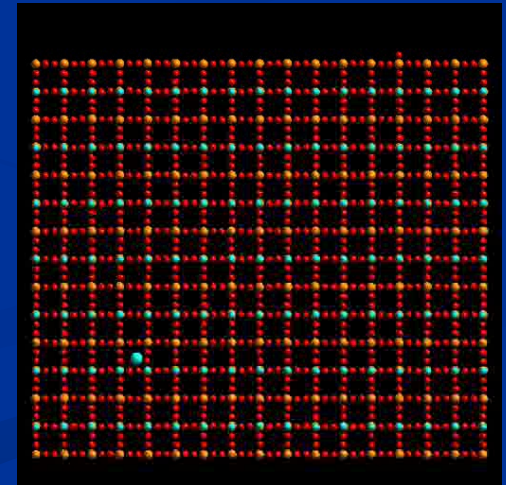
**Queen Mary University of London**

# **Classical molecular dynamics simulations**

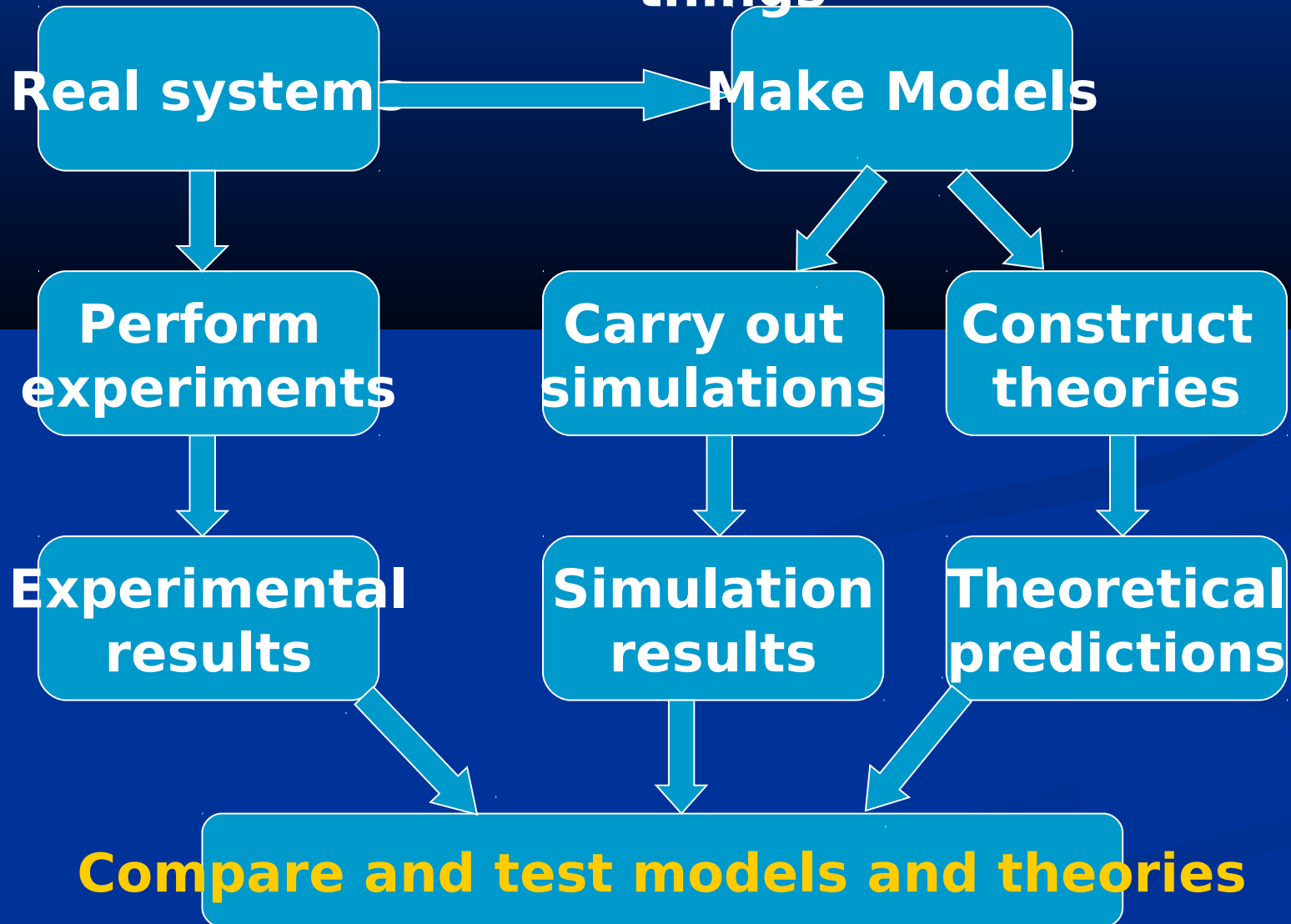
- 1. Overview of the method**
- 2. Interatomic forces**
- 3. Details and tricks of MD**
- 4. Data analysis**
- 5. Examples from recent science**

# Short history

- The need to simulate liquids (Allen and Tildesley “Computer simulation of *liquids*”)
- First simulation done in 1953 in Los Alamos
- A direct route from the microscopic details of a system to macroscopic properties
- Understand and interpret the experiments
- Academic and technological importance
- Complement the experiments, when it is impossible to carry out experiments at extreme conditions or access very short length scales and time scales



# How it works in a grand scheme of things





# Main idea of Molecular Dynamics simulations

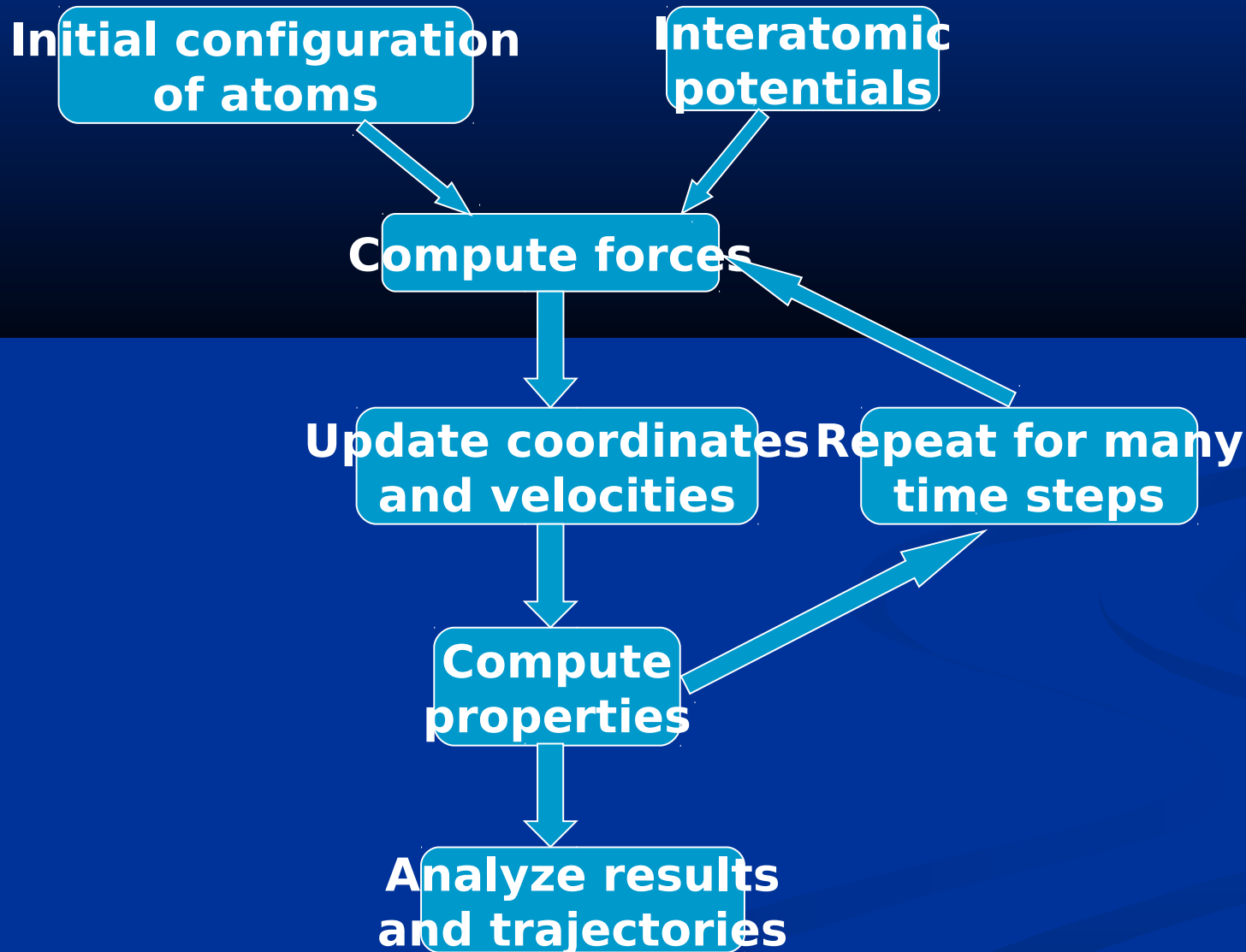
$$\begin{aligned}\vec{F} &= m \frac{d\vec{v}}{dt} \\ \vec{F} &= - \frac{\partial U(\vec{r})}{\partial \vec{r}}\end{aligned}$$

- Solve these equations approximately, by substituting differential equations by finite difference equations:

$$\vec{F} = m \frac{d\vec{v}}{dt} \approx m \frac{\Delta \vec{v}}{\Delta t} \Rightarrow \Delta \vec{v} \approx \frac{\vec{F} \Delta t}{m} \Rightarrow \vec{v}_{new} = \vec{v}_{old} + \frac{\vec{F} \Delta t}{m}$$

- For  $\Delta t \rightarrow 0$ , the above is exact. Acceptable  $\Delta t$  is a tradeoff between efficiency and precision, dictated mostly by conservation laws (mainly energy)
- $\Delta t$  should be much smaller than a typical period of atomic vibrations of 0.1 ps. A typical empirical value of timestep is

# A typical MD algorithm:



# A typical MD algorithm

- There are different algorithms for calculating the trajectories
- They vary in accuracy, drift and noise
- Verlet is a popular, good quality integration

algorithm:

$$r(t + \Delta t) = r(t) + \Delta t v(t) + \frac{1}{2} \Delta t^2 a(t) + \dots$$

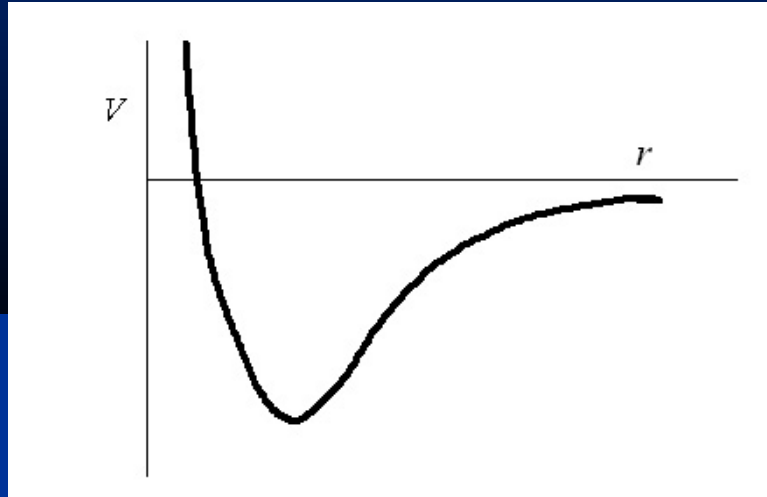
$$r(t - \Delta t) = r(t) - \Delta t v(t) + \frac{1}{2} \Delta t^2 a(t) - \dots$$

$$r(t + \Delta t) = 2r(t) - r(t - \Delta t) + \Delta t^2 a(t) + O(\Delta t^4)$$

$$v(t) = \frac{r(t + \Delta t) - r(t - \Delta t)}{2\Delta t} + O(\Delta t^2)$$

# Empirical potentials: a brief introduction

$$\vec{F} = -\frac{\partial U(r)}{\partial r}$$



$v(r)$  is given as an input in MD simulations to describe interatomic forces

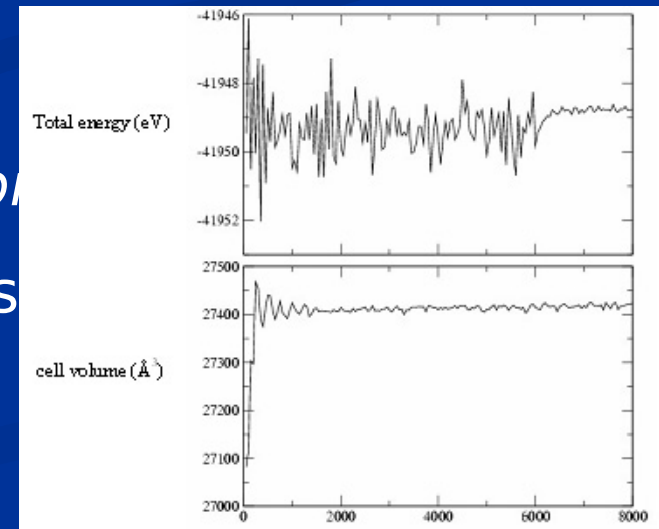
We will talk about potentials in more details later on in the course

# Stages of MD simulation: initialisation, equilibration, production

- Initial structure (collection of atomic coordinates) is a standard input
- Initial velocities are given, often with a Maxwellian distribution corresponding to a specified temperature.

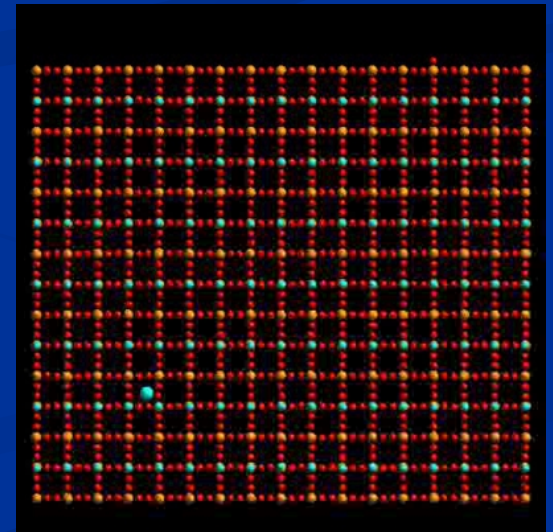
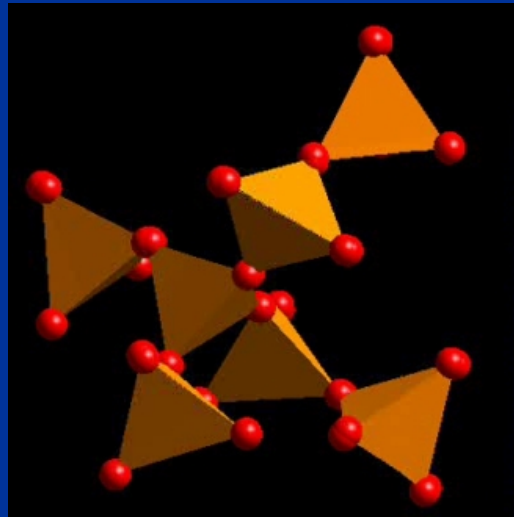
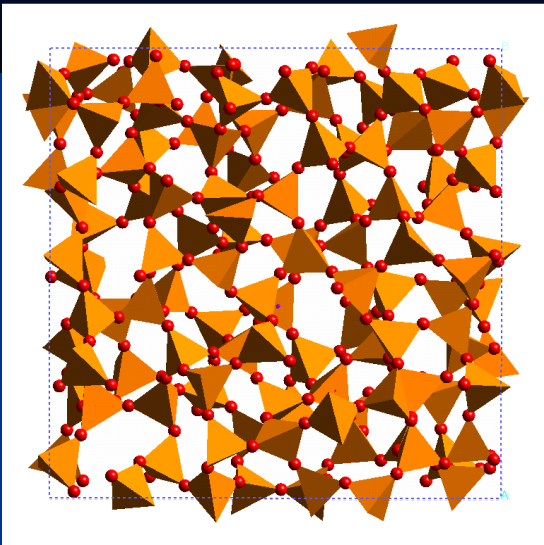
$$\vec{P} = \sum_{i=1}^N m_i \vec{v}_i = 0$$

- Initial velocities conform to
- The structure evolves to the *equilibrium*
- After this we reach the *production* stage and collect the data we need



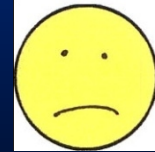
# What can we calculate?

- Structure
- Dynamics
- Emergent/collective behaviour



## The actual code

- There was a time when everyone would write their own MD code...

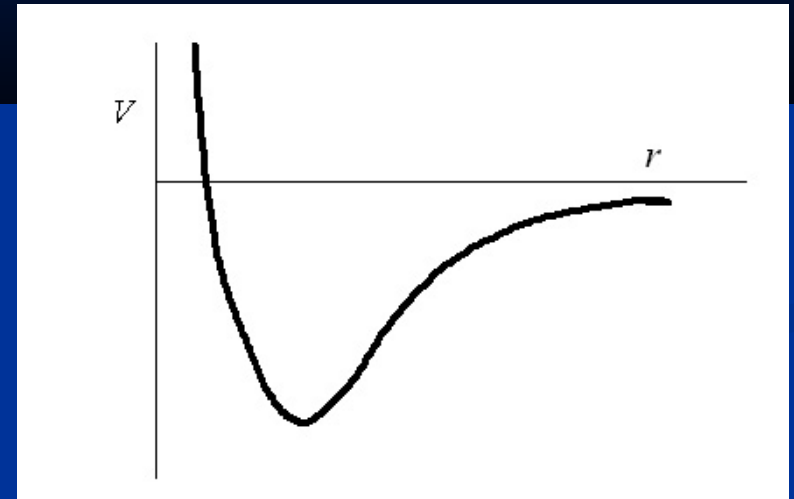
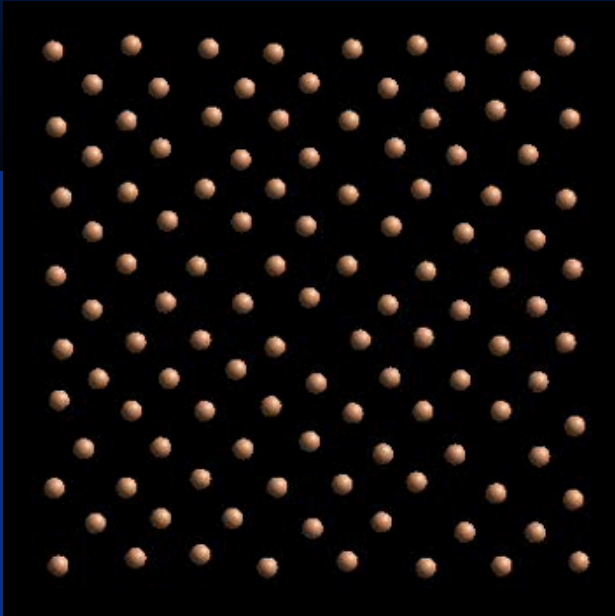


- Nowadays there are a number of good quality, off-the-shelf, codes. DL\_POLY is arguably the top classical MD package around (and it's free!). An online version of the manual is at:

[http://www.cse.scitech.ac.uk/ccg/software/DL\\_POLY](http://www.cse.scitech.ac.uk/ccg/software/DL_POLY)

- We are using DL\_POLY, arguably one of the best around

# Interatomic interactions



$$\vec{F} = - \frac{\partial V(\vec{r})}{\partial \vec{r}}$$



# Interatomic forces

- The interatomic interaction is due to the electromagnetic (electrostatic) forces
- Quantum-mechanical nature of interatomic interactions (i.e. why is H atom stable?)

$$H\psi = \left( -\frac{\hbar^2}{2m} \nabla^2 + V(r) \right) \psi = E\psi$$

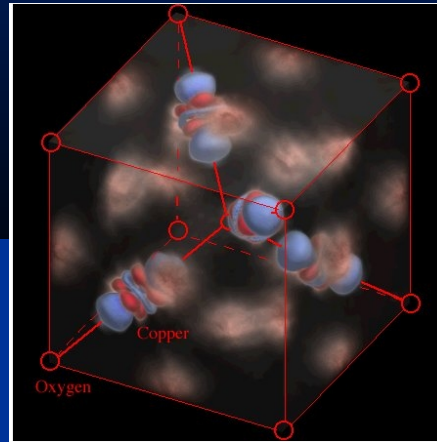
- $V(r)$  is the Coloumb interaction.
- For many atoms, it also includes quantum-mechanical terms related to quantum statistics (e.g. exchange energy term)
- The change in  $V$  as a result of change of  $r$  gives rise to a force that can be calculated

# Interatomic forces

- Why not do full quantum-mechanical calculations?
- Empirical potentials give worse accuracy but access to larger system sizes and longer simulation times
- ~100 atoms in ab-initio (density functional theory methods) in terms of size and several tens of ps in terms of time
- ~100 millions of atoms in classical MD simulations in terms of size and up to ms in terms of time
- Many collective and emergent phenomena can only be studied using classical MD, because they involve many atoms

# MD empirical potentials

Forget about quantum mechanics,  
electrons,  
and their complex distribution



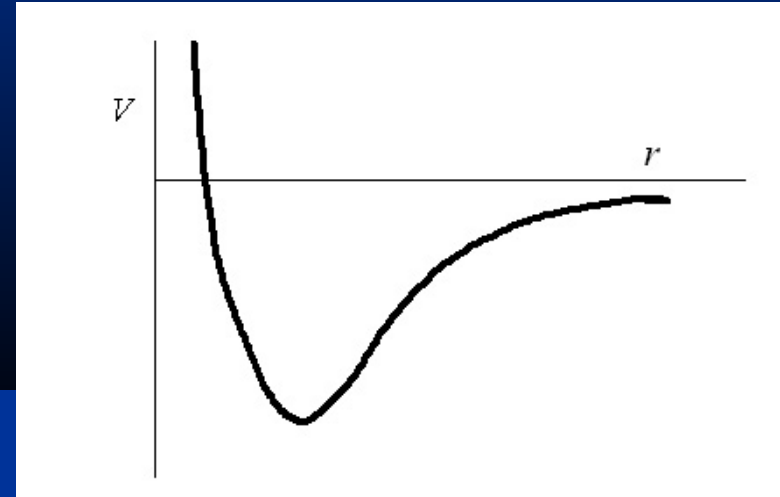
Think balls (points) interacting via a given empirical potential



# MD empirical potentials

A typical empirical potential often includes:

Lennard-Jones  $V(r)=A/r^{12}-B/r^6$  or  
Buckingham-type potentials  
 $V(r)=A*\exp(-r/\rho)-B/r^6$



and Coulomb interactions  $V(r)=\frac{q_1 q_2}{r}$  (Pauli principle)

- Strong short-range repulsion (Pauli principle)
- Weaker attraction. Can include Van del Waals dipole interactions:

For neutral atoms,  $q=0$ . Also,  $\langle p_1 \rangle = \langle p_2 \rangle = 0$  in average for non-interacting atoms.

However, a fluctuating dipole on atom 1 generates electric field  $E \sim p_1/r^3$ , which induces an instantaneous extra dipole on atom 2  $\Delta p_2 \sim E \sim p_1/r^3$ . The additional energy is  $V \sim -p_1 \Delta p_2 / r^3 \sim -1/r^6$

- Van del Waals interactions are weak, and come in addition to

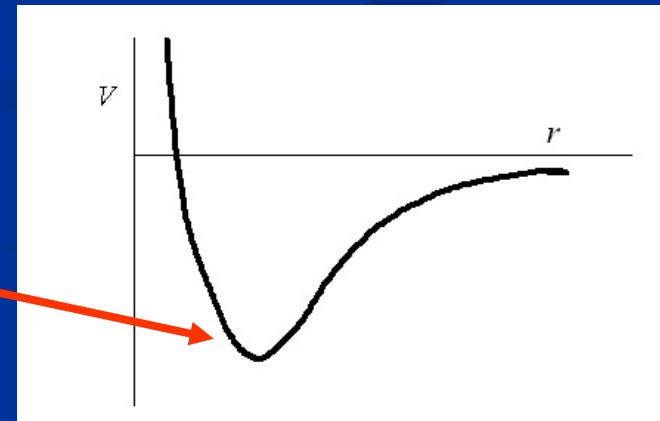
# MD empirical potentials

At very close approach ( $r < 0.5 \text{ \AA}$ ), “screened Coulomb potential” generally applies:

$V(r) \sim \exp(-r/\rho)/r$ , where  $\rho$  is the screening radius

Encountered at either very high temperatures ( $T > 100,000 \text{ K}$ ) or in radiation damage

- We are often interested in small-amplitude vibrations anyway, where harmonic approximation applies



# MD empirical potentials

Lennard-Jones  $V(r)=A/r^{12}-B/r^6$  or Buckingham-type potentials  
 $V(r)=A*\exp(-r/\rho)-B/r^6$

and Coloumb interactions  $V(r)=\alpha q_1 q_2 / r$

with parameters and charges chosen to reproduce material's properties

## Two main methods:

- Fitting to experimental data (structure and elasticity)
- Fitting to the results of quantum-mechanical calculations (either to structure and elasticity, or to the calculated potential energy surface)

Good empirical potentials give ~1% agreement with experimental lattice constants and ~10% agreement with bulk modulus

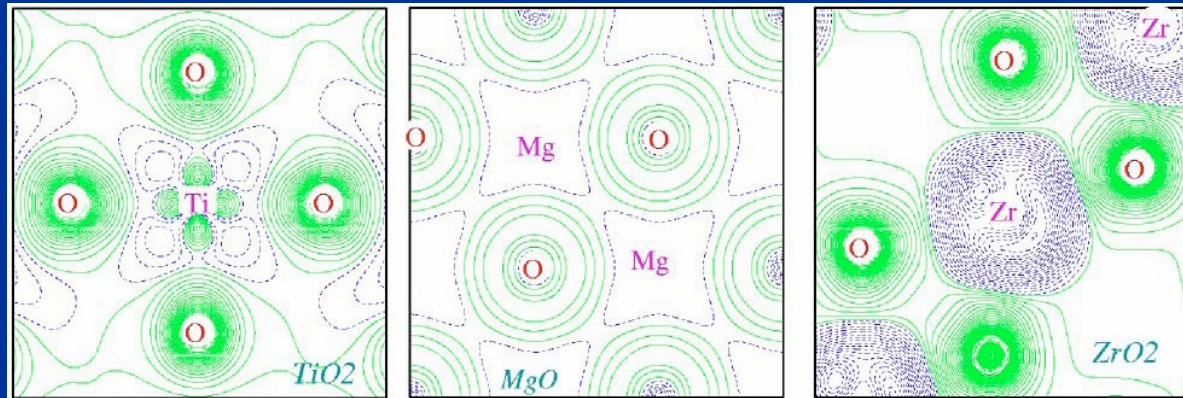
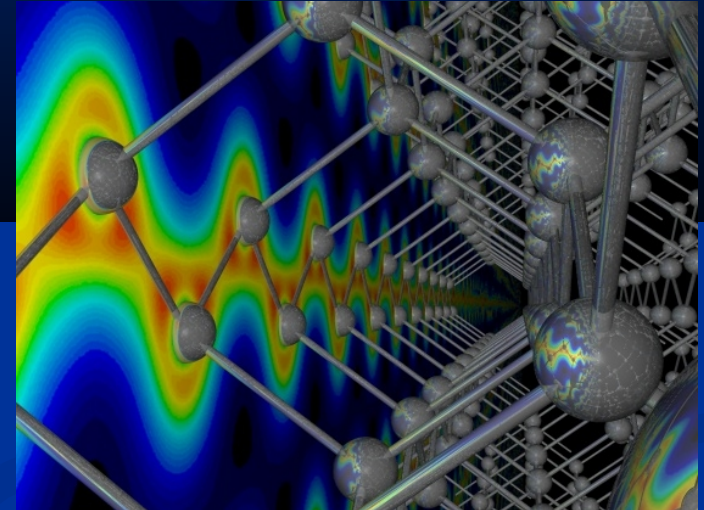
Selecting the parameters can depend on the nature of the chemical bond in a material

# Main types of interatomic interactions and bonds

- Charge transfer and electronegativity (Pauling)
- Ionic (MgO, NaCl)
- Covalent (Si, C)
- Most materials are mixed

Pauling and Phillips ionicity measures  
 $\text{SiO}_2$  is  $\sim 50\%$  ionic and  $\sim 50\%$  covalent

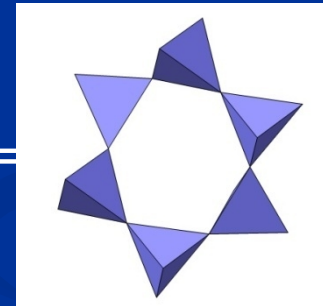
- Metallic (Fe, Ni)



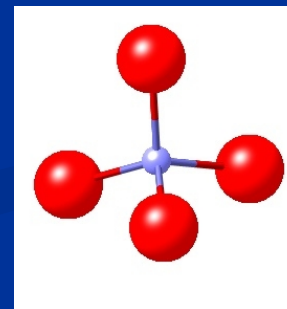
# Main types of interatomic interactions and bonds

- Depending on the nature of the chemical bond, charges can be added or adjusted in the force field of empirical potentials
- No charges for Si or Ge
- Full (formal) charges for MgO or NaCl  $q = \pm 1$

- Partial charges for SiO<sub>2</sub> ,  $q_{\text{Si}} = 2.4$ ,  $q_{\text{O}} =$



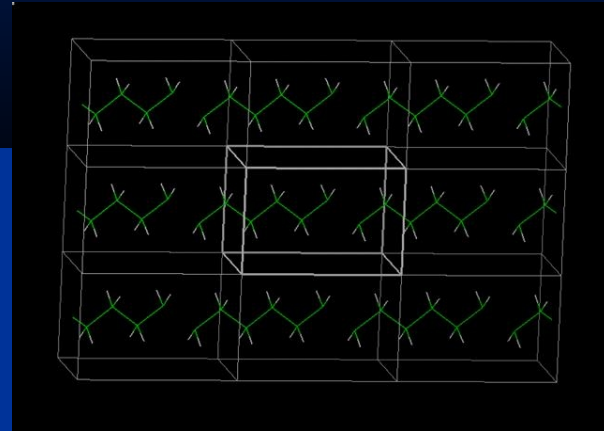
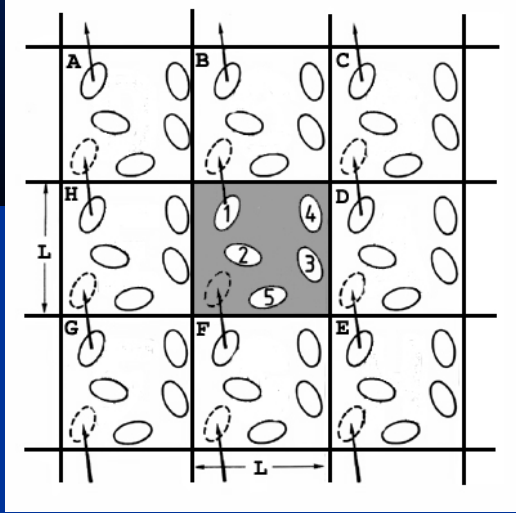
- 3-body forces can be used to reflect covalency (e. g. in Si):  
 $V(\beta) = 1/2 * k * (\beta - \beta_0)^2$





# Periodic boundary conditions

Why have periodic boundaries?



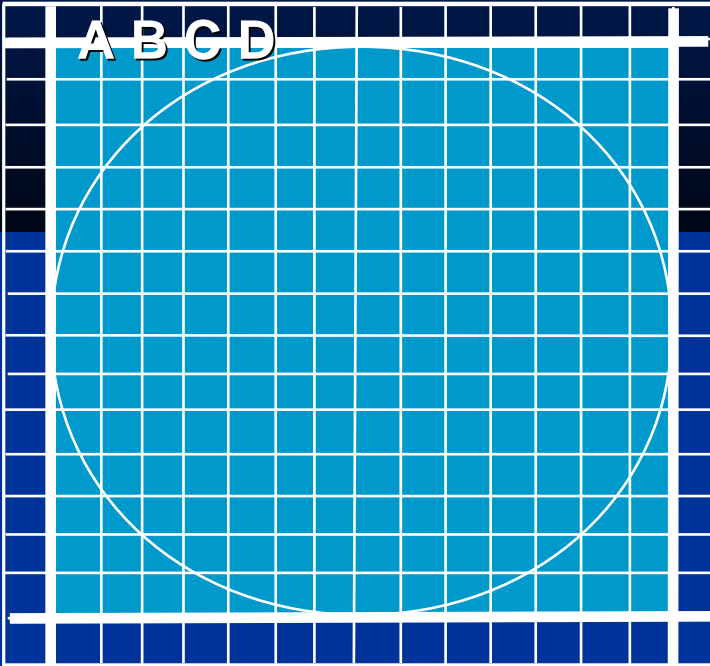
# Running in parallel



Two popular strategies:

1. Replicated data strategy
2. Domain decomposition strategy

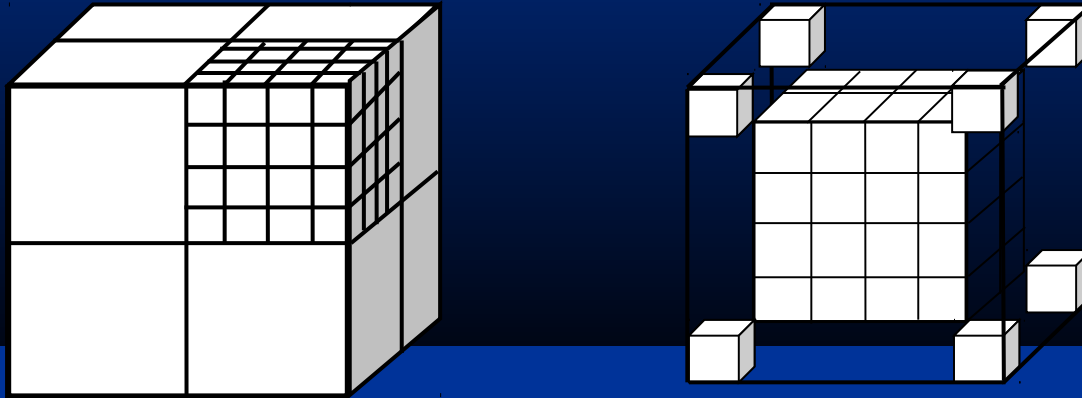
# Replicated data strategy



Each processor sees the whole system

Each processor calculates a particular type of force (LJ, Coloumb etc)

# Domain Decomposition Strategy

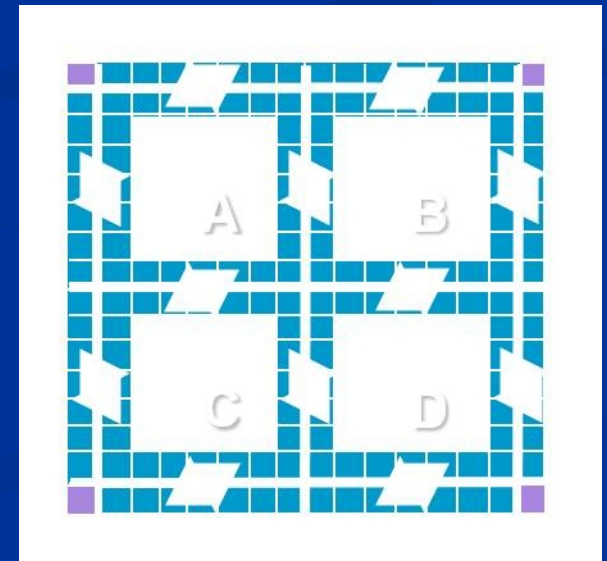


Each processor simulates a  
geometrically different part of the  
system (forces, velocities, positions)

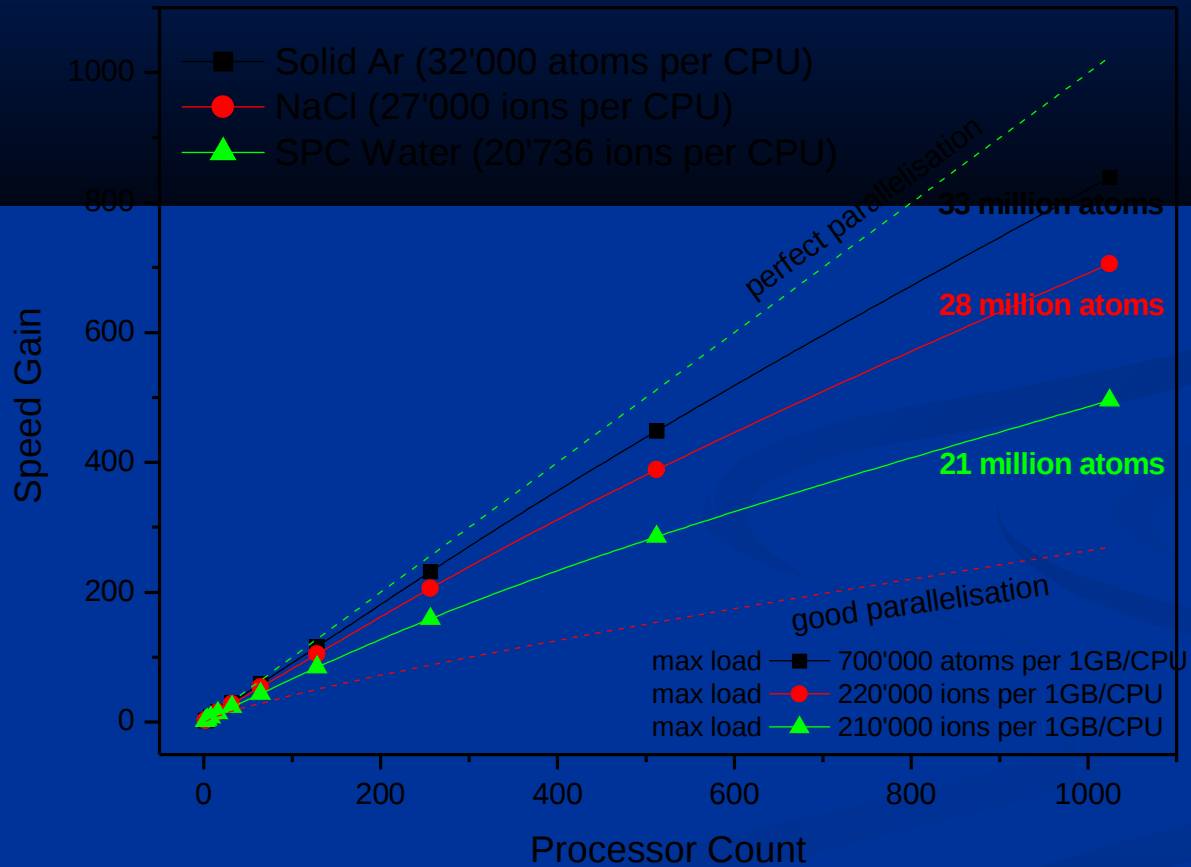
**independently**

Processors communicate through the  
boundaries

Very well suited for very large systems



# Parallelisation efficiency



## **MD simulations of very large systems**

(stimulated by large systems in radiation damage)

300,763,000 NaCl with full electrostatics evaluation on  
1024 CPU cores

Timestep time  $\approx$  60 seconds (1 second on the new  
HPC with 16 thousands of parallel processors)

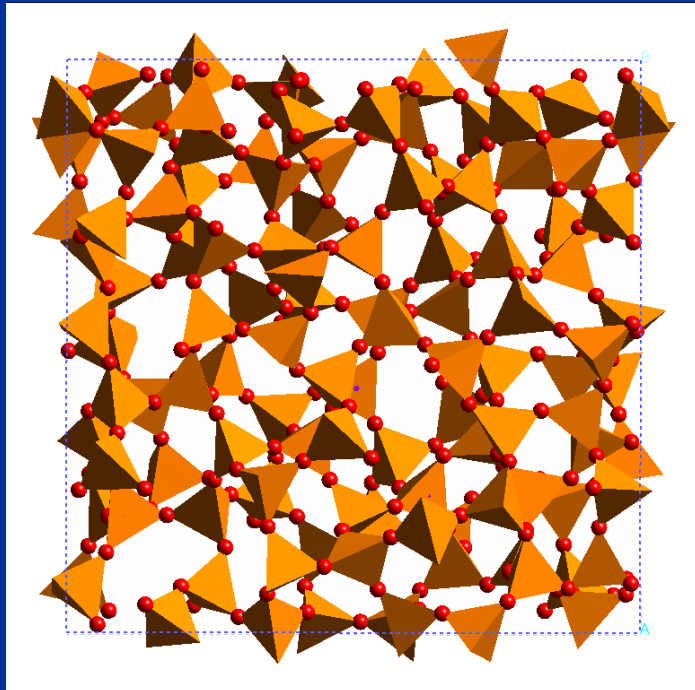
(world record by a general MD package)

$\sim$ 1 billion atoms on 16,000 parallel processors, system  
size approaches one micrometer !

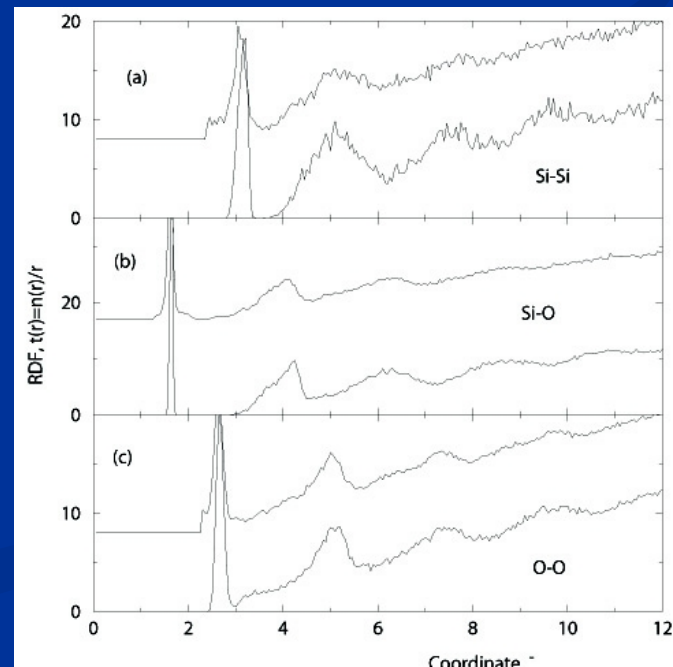
MD simulations meet many important effects and  
experiments at this length scale (eg microcracks,  
composite materials, interfaces, proteins, biomolecules  
)

# What can we calculate?

- Structure
- Dynamics
- Emergent behaviour

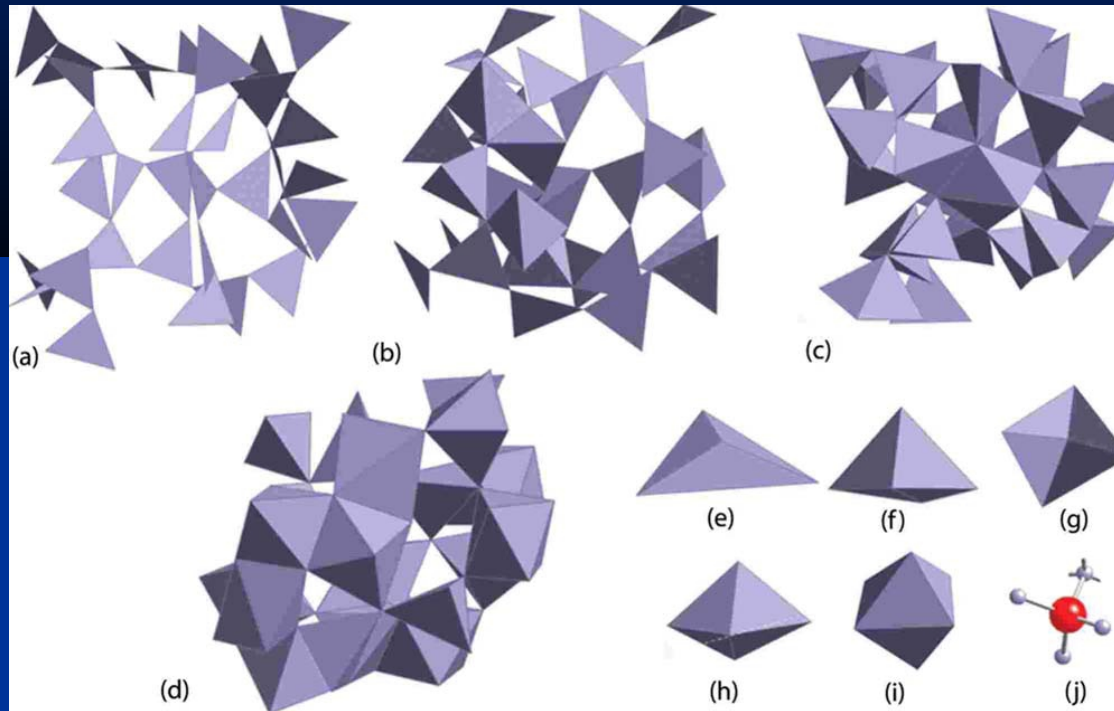


## Radial distribution functions

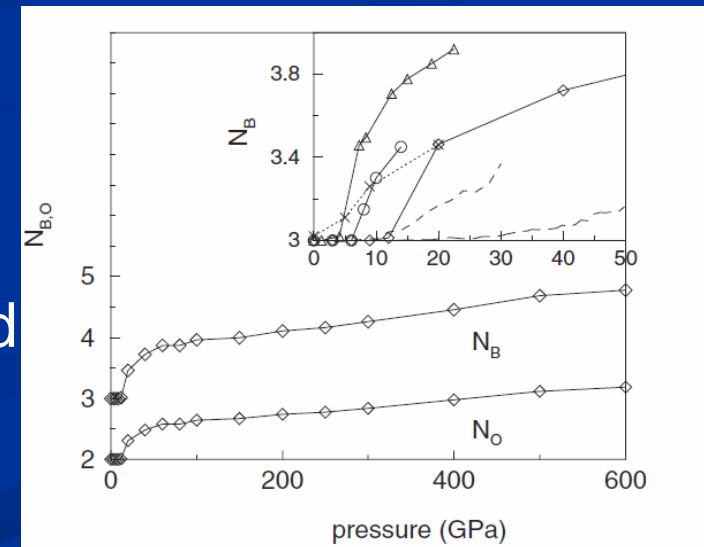


# Analysis of local structure (B2O3 glass under pressure)

away from averages (RDFs). Look at the particular local structural modifications



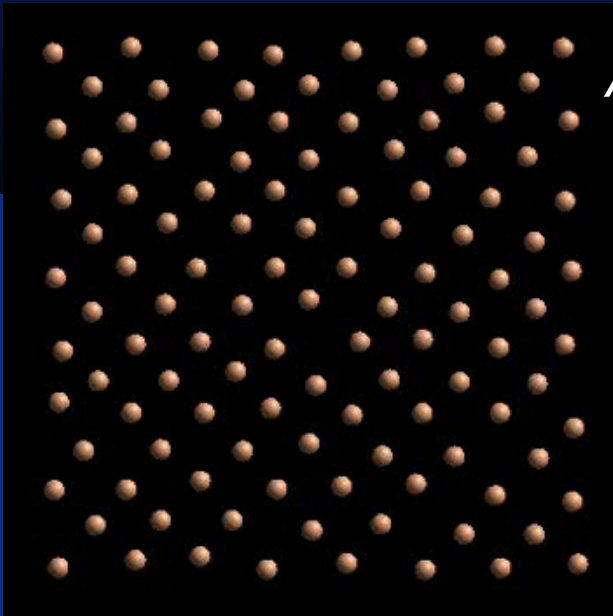
see with experiments at low pressure and  
predict behaviour at very high pressure  
up to 600 GPa





# What can we calculate - examples of dynamics

## Phonons



$A(t)$  that depends on positions and velocities  
The “autocorrelation function” is defined as

$$C_{AA}(t) = \langle A(t)A(0) \rangle = \frac{1}{t_{\max}} \sum_{t_0=1}^{t_{\max}} A(t_0)A(t_0 + t)$$

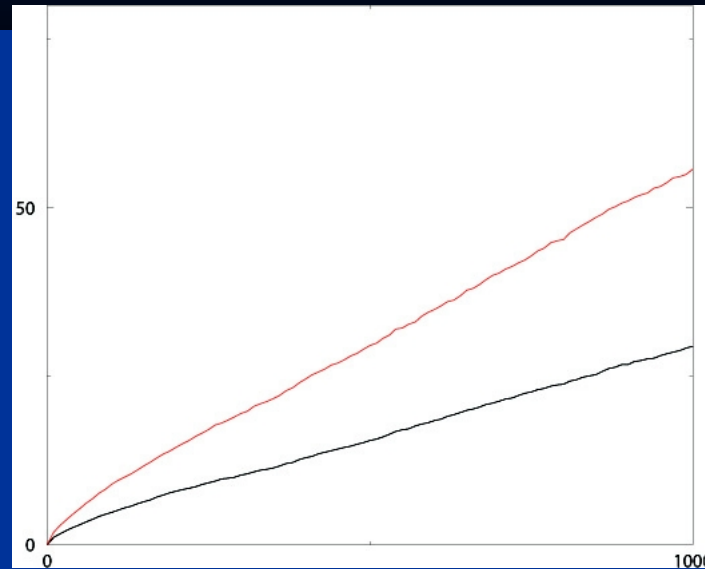
Can calculate velocity-velocity correlation function  
and phonon density of states

# Analyze dynamics: transport properties

Einstein relation  $\langle (r - \langle r \rangle)^2 \rangle = 6Dt$

From atomic coordinates, calculate diffusion coefficient  $D$

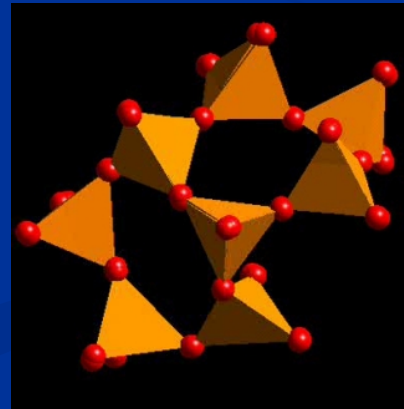
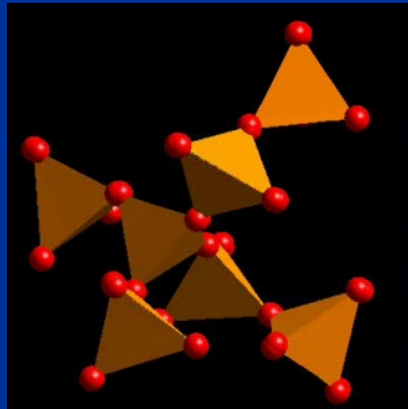
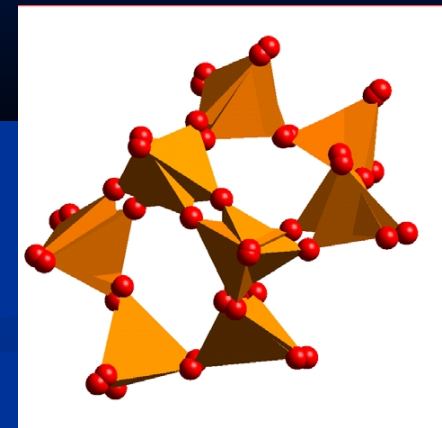
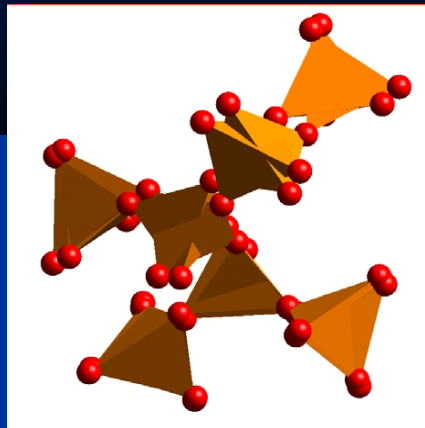
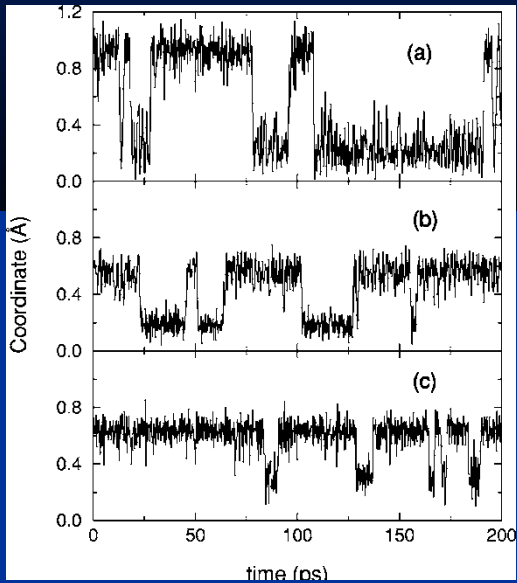
MSD



Time

# What can we calculate - examples of dynamics

## Two-level systems in glasses

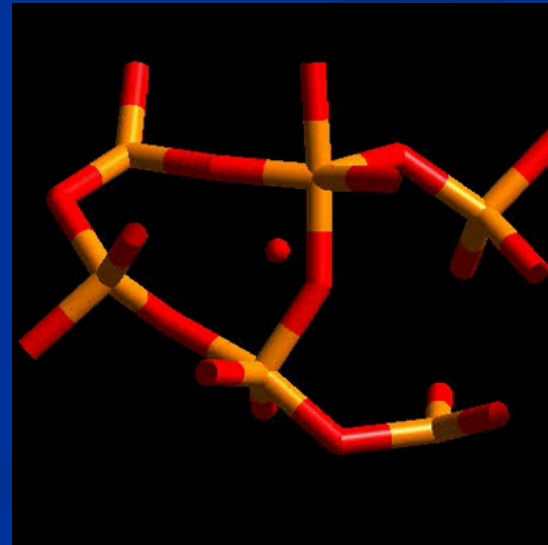


# Analysis of local structure

Silica glass under high pressure

Glasses relax very slow,  $q \sim \ln(t)$

**Can relax longer than the age of the Universe!**

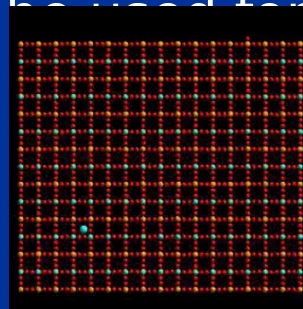


# Radiation damage effects in ceramics

- Motivation: pressing need to safely encapsulate radioactive nuclear waste that comes from power plants and surplus plutonium
- HLW accounts for 95% of the total radioactivity produced during nuclear electricity generation. The amount of HLW worldwide is increasing by 12,000 metric tons a year, equivalent to 100 double-decker buses
- Pu stockpile in the UK: ~100 metric tons (reprocessed from waste and from decommissioned weapons), of which 20 tons has been declared as waste (Am)



proposed to be used for encapsulation



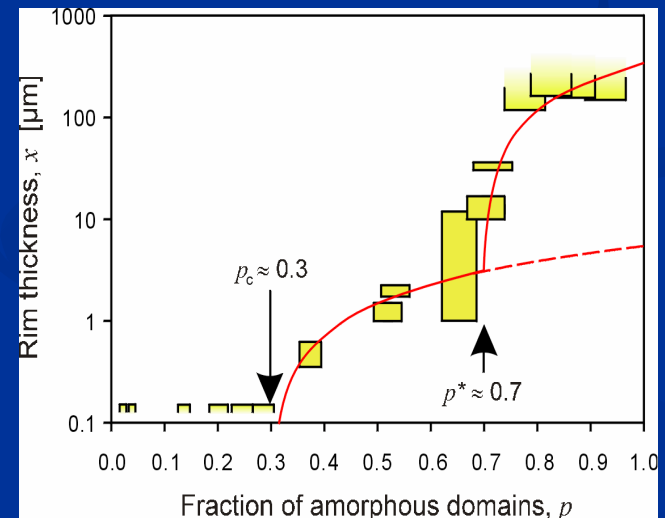
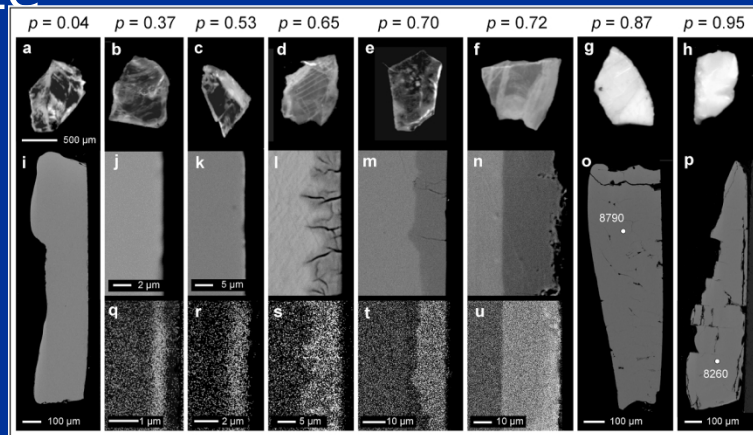
Actinides are long-lived. A waste form should be stable during millions of years. Traditional glasses are not an option. UK NDA wants to use ceramics.

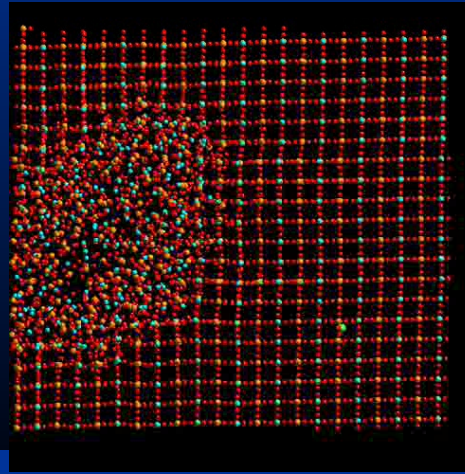
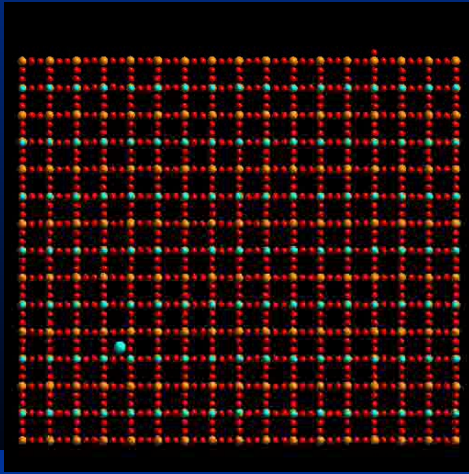
# Effect of radiation-induced amorphization on diffusion

Case study: zircon  $\text{ZrSiO}_4$  found minerals are  $\sim 1$  billion years old, completely amorphous yet intact



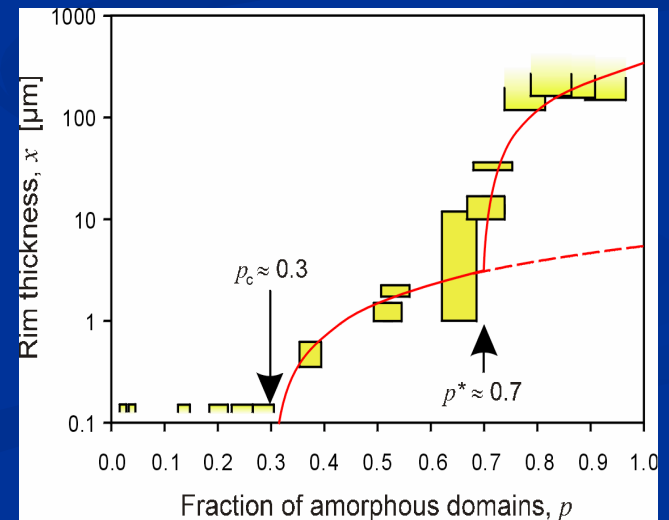
Absorbs large ions like Pu on Zr site





Channels of low density appearing along the track

This gives channels of increased diffusion and explains percolation-type increases of transport





# Resistant vs amorphizable materials

$\text{Gd}_2\text{Ti}_2\text{O}_7$  – “official” US Department of Energy waste form. Amorphizes easily under irradiation

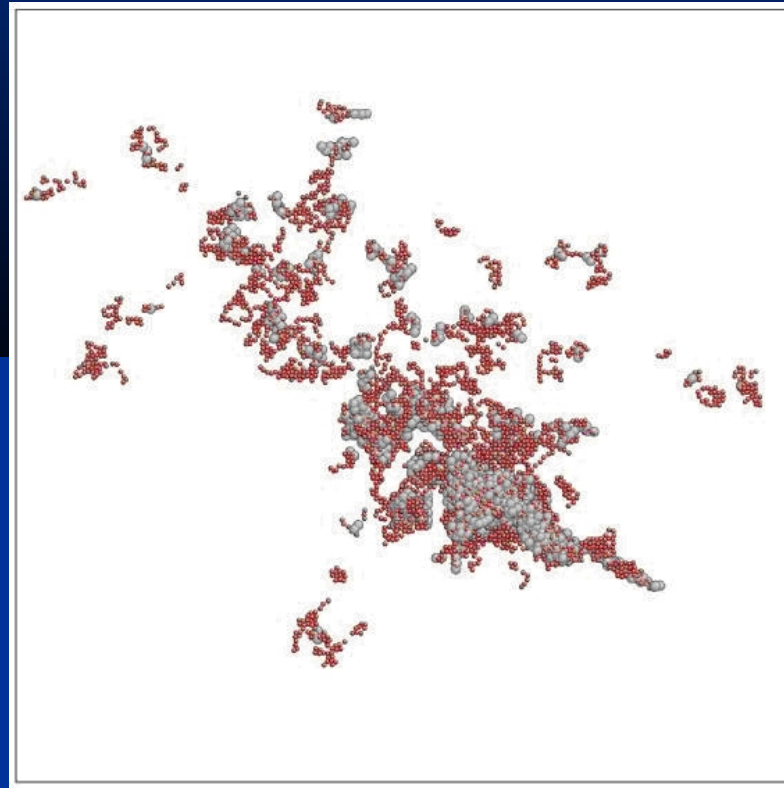
$\text{Gd}_2\text{Zr}_2\text{O}_7$  – does not amorphize even at very large radiation doses!

**What is the nature of the process of resistance to amorphization by radiation damage?**

Also important in fusion reactors: 14 MeV neutrons, ~1 MeV recoils, 200 dpa over reactor lifetime. **No experiments are possible!**



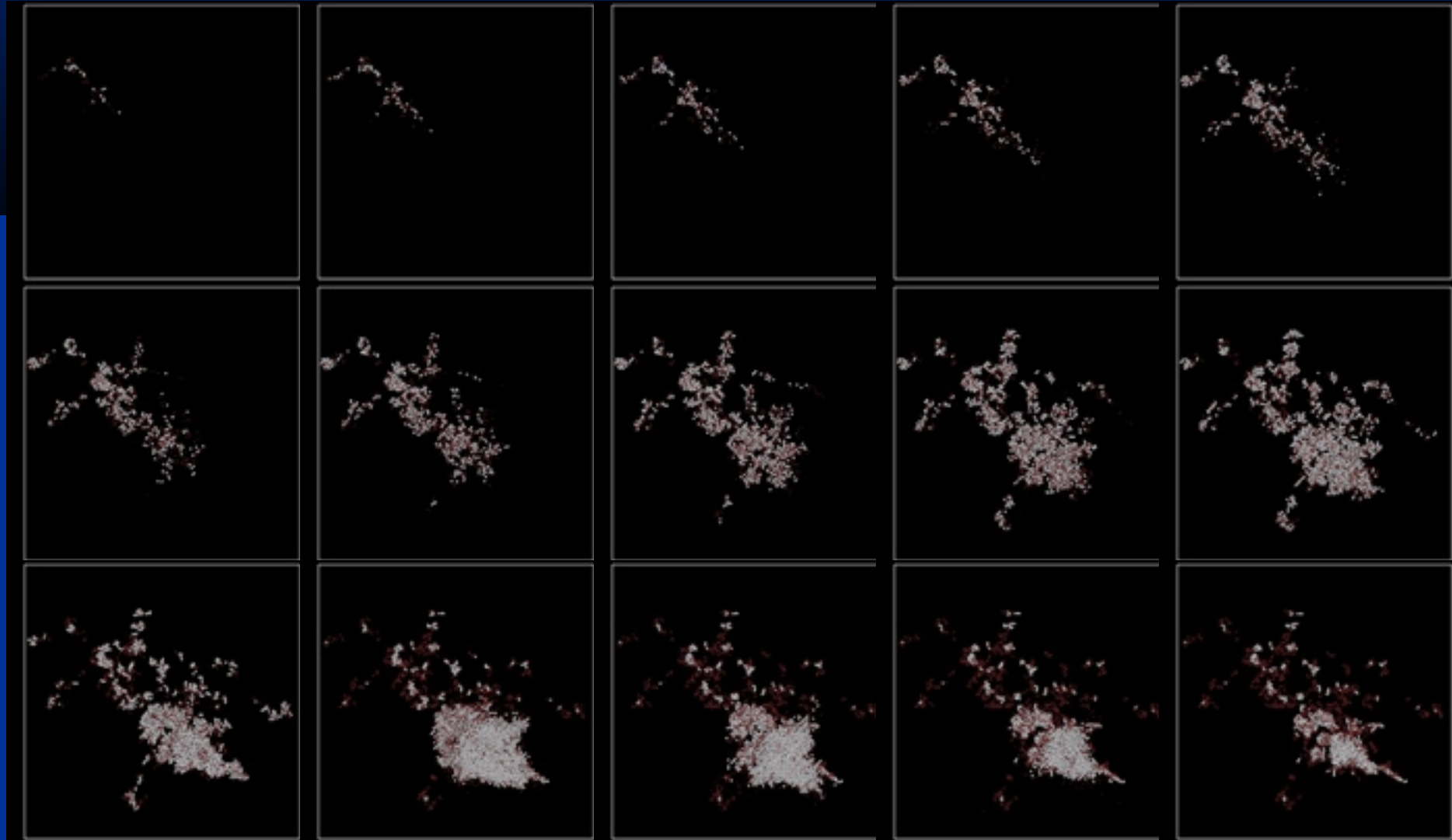
# Modelling resistance to amorphization by radiation damage



- 100 keV in rutile  $\text{TiO}_2$ , ~5-10 mln atoms, MD box size is ~500 Å
- 512-1024 parallel processors

# Look at the process in detail

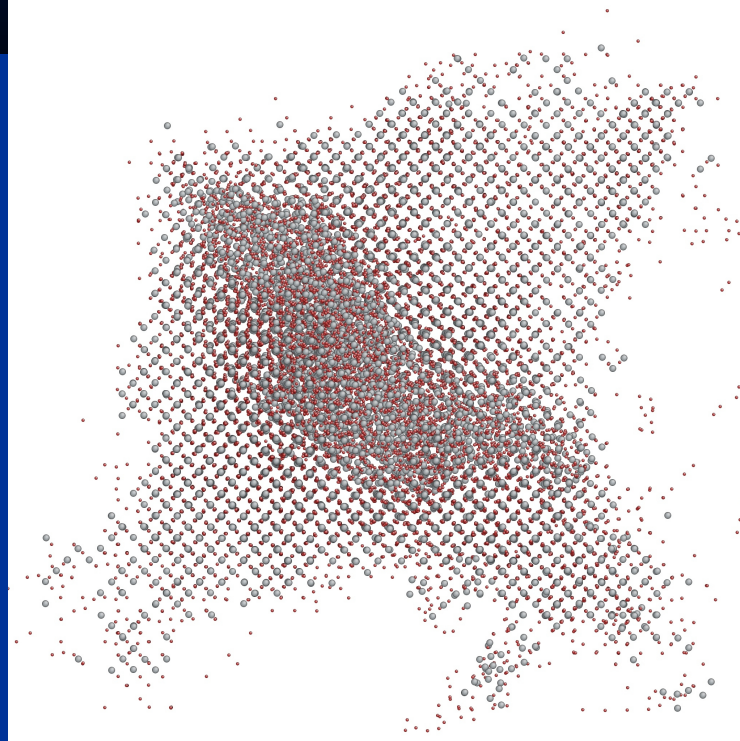
## Rutile $\text{TiO}_2$



## Two types of relaxation:

1. Elastic relaxation. Reversible.
2. Relaxation and recovery of the true structural damage

Both happen on the few picosecond timescale.





# Resistance to amorphization

50 keV U  
recoil

Poor recovery Intermediate recovery Good and perfect recovery

$\text{SiO}_2$

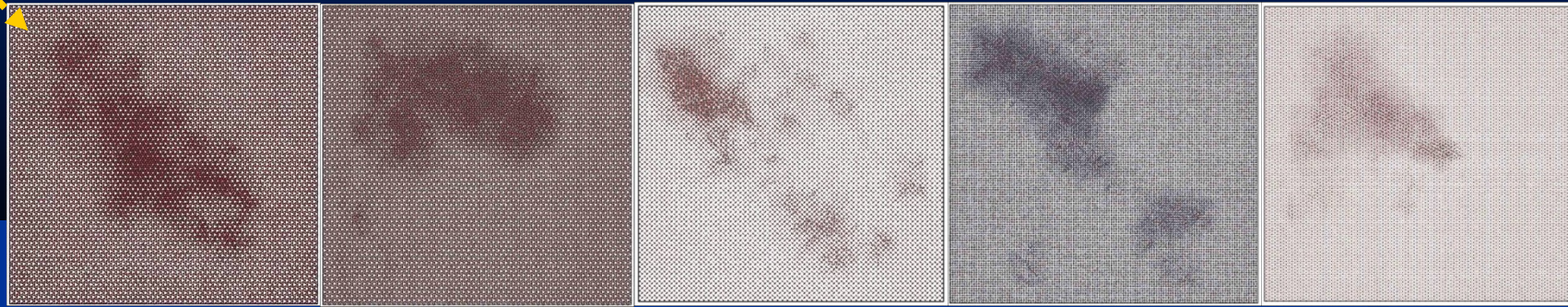
$\text{GeO}_2$

$\text{TiO}_2$

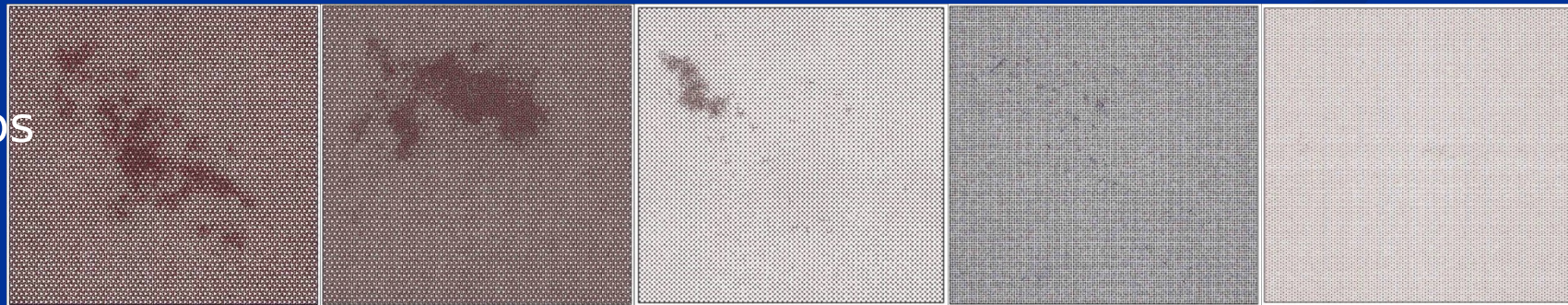
$\text{MgO}$

$\text{Al}_2\text{O}_3$

$t=1$  ps



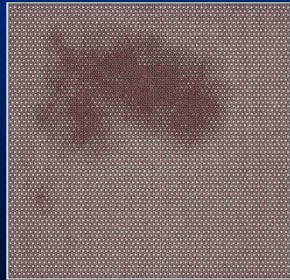
$t=5, 50$  ps



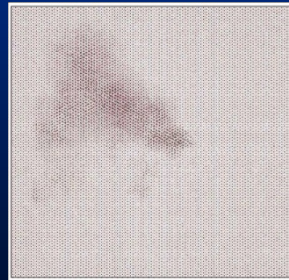
Calculations **reproduce** experimental behaviour of resistance to amorphization  
barriers correlate with the curvature of the potential at equilibrium

# Resistance to amorphization

$t=1$  ps

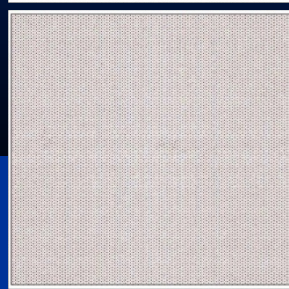
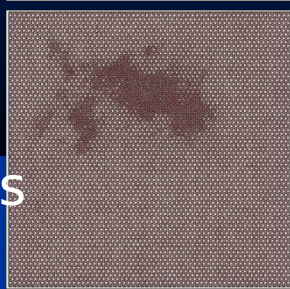


$\text{GeO}_2$

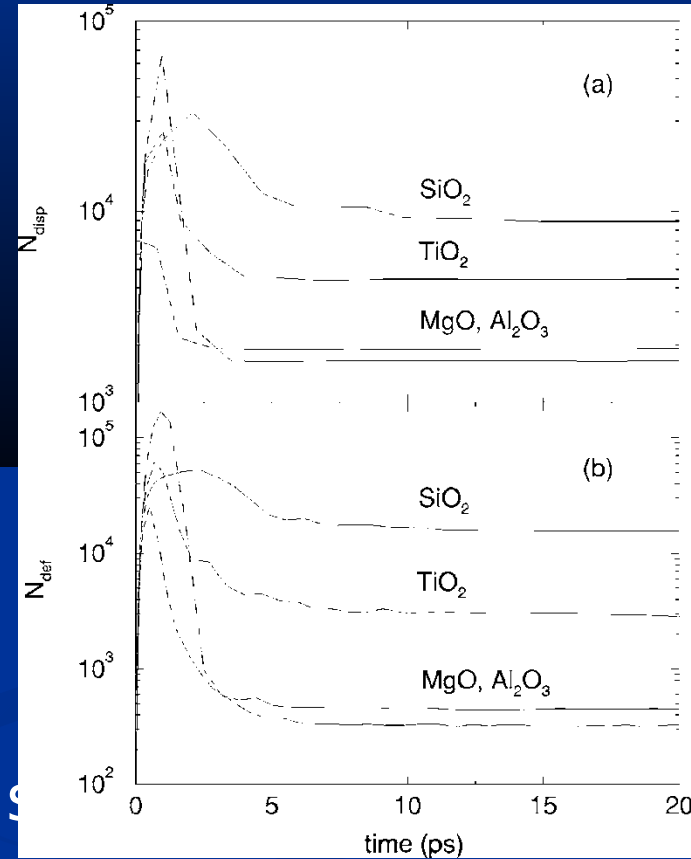


$\text{Al}_2\text{O}_3$

$t=5, 50$  ps



- Time scales of damage recovery: s
- Correlate the details of interatomic potentials with damage recovery: damage increases with the **stiffness** of O-O interaction





# Limitations of MD simulations

1. Simulations are limited by the accuracy of empirical interatomic potentials
2. The use of finite-size sampled and periodic boundary conditions
  - (a) interactions with reappearing waves is not understood
  - (b) the use of finite sizes restricts the range of allowed wave vectors(although this becomes of less an issue with massive parallel computers)
3. Short simulation times
  - (a) may not be enough time to explore its phase space and have an ergodic system
  - (b) may not be enough time to observe a phenomenon that lasts longer than simulation time

**But because these limitations are different from those in theory and experiment, a combination of MD with**

**Thank you!**

**PhD opportunities** in condensed matter physics  
in Queen Mary University of London:

Theory  
Simulations  
Experiment

Email <k.trachenko@qmul.ac.uk>